## YK700~1000XP

## Arm length 700 800 1000 mm/Maximum payload 20 kg

## Robot ordering method

YK788XP-200-**1000** 

**3L** -

400:400mm

- 3L:3.5m - 5I :5m 10L:10m **RCX142 - E** 

R - N1-CC-S

Blank:Standard
E:CE specification

Controller type: Refer to the Controller Catalog for further details

\* Built-to-order product. Contact us for the delivery period.

## Basic specifications

Model			YK700XP	YK800XP	YK1000XP
	X axis	Arm length	350mm	450mm	550mm
Axis specifications		Rotation range	± 120°		
	Y axis	Arm length	350mm 450mm		450mm
		Rotation range	± 145°		
	Z axis	Stroke	200mm, 400mm		
	R axis	Rotation range	± 180°		
Motor		X axis	800W		
		Y axis	400W		
		Z axis	400W		
		R axis	200W		
Maximum speed		X, Y combined	6.7m/s	7.3m / s	8.0m/s
		Z axis	1.7m/s		
		R axis	600°/s		
Repeatability*1		X,Y axis	± 0.02mm		
		Z axis	± 0.01mm		
		R axis	± 0.005°		
Max. payload			20kg		
Standard cycle time (with 2kg payload)			0.57 sec. 0.60 sec		0.60 sec.
R axis allowable moment inertia*2			0.314kgm² (3.2kgfcms²)		
User wiring			0.2sq × 20 wires		
User tubing			ø6 × 3		
Movement limit setting			1. Soft limit, 2. Mechanical limit (X, Y, Z axes)		
Robot cable			Standard 3.5m Option: 5m, 10m		
Controller, Power supply capacity			RCX142-R, 2000VA		
Weight			56kg	57kg	58kg



**YK700XP** 

- \*1: This is the value at a constant ambient temperature. (X, Y axes)
- \*2: There are limits to the setting of the acceleration coefficient.





