## Arm length 300 • 400 mm/Maximum payload 3kg

## Robot ordering method

YK300XS-

— 3L:3.5m — 5L:5m

10L:10m

**RCX142** 

- F:CF specif

Controller type: Refer to the Controller Catalog for further details.

## Basic specifications

Model			YK300XS	YK400XS
Axis specifications	X axis	Arm length	175mm	225mm
		Rotation range	± 115°	
	Y axis	Arm length	125mm	175mm
		Rotation range	± 140°	
	Z axis	Stroke	150mm	
	R axis	Rotation range	± 180°	
Motor		X axis	200W	
		Y axis	100W	
		Z axis	100W	
		R axis	100W	
Maximum speed		X, Y combined	4.4m / s	6.0m/s
		Z axis	1.0m/s	
		R axis	1020°/s	
Repeatability*1		X,Y axis	± 0.01mm	
		Z axis	± 0.01mm	
		R axis	± 0.005°	
Max. payload			3kg	
Standard cycle time (w		vith 2kg payload)	0.54 sec.	0.66 sec.
R axis allowable moment inertia*2			0.049kgm² (	0.5kgfcms <sup>2</sup> )
User wiring			0.2sq × 10 wires	
User tubing			ø4 × 3	
Movement limit setting			1. Soft limit, 2. Mechanical limit (X, Y, Z axes)	
Robot cable			Standard 3.5m Option: 5m, 10m	
Controller, Power supply capacity			RCX142, 1000VA	
Weight			15kg	

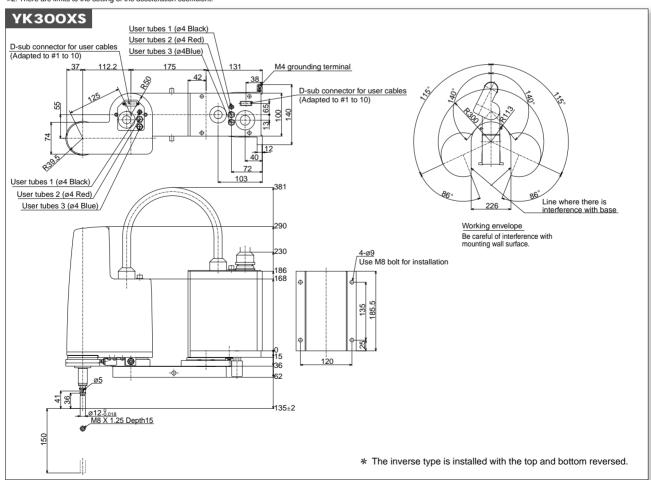
\*1: This is the value at a constant ambient temperature. (X, Y axes) \*2: There are limits to the setting of the acceleration coefficient.



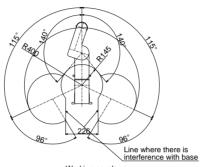
YK300XS (wall-hanging)



YK300XS (inverse wall-hanging)



## YK400XS



Working envelope
Be careful of interference with mounting wall surface.

