YK250~400XP

Arm length 250 • 350 • 400 mm/Maximum payload 3kg

Robot ordering method

3L - 3L:3.5m

5L:5m 10L:10m **RCX142**

* Built-to-order product. Contact us for the delivery period.

Controller type: Refer to the Controller Catalog for further details.

Basic specifications

Model			YK250XP	YK350XP	YK400XP
Axis specifications	X axis	Arm length	125mm 225mm		
		Rotation range	± 115°		
	Y axis	Arm length	125mm 175mm		175mm
		Rotation range	± 130° ± 140°		± 140°
	Z axis	Stroke	150mm		
	R axis	Rotation range	± 180°		
Motor		X axis	200W		
		Y axis	100W		
		Z axis	100W		
		R axis	100W		
Maximum speed		X, Y combined	4.0m/s	5.0m/s	6.0m/s
		Z axis	1.0m / s		
		R axis	1020°/s		
Repeatability*1		X,Y axis	± 0.01mm		
		Z axis	± 0.01mm		
		R axis	± 0.005°		
Max. payload			3kg		
Standard cycle time (with 2kg payload)			0.54	sec.	0.66 sec.
R axis allowable moment inertia*2			0.049kgm² (0.5kgfcms²)		
User wiring			0.2sq × 10 wires		
User tubing			ø4 × 3		
Movement limit setting			1. Soft limit, 2. Mechanical limit (X, Y, Z axes)		
Robot cable			Standard 3.5m Option: 5m, 10m		
Controller, Power supply capacity			RCX142, 1000VA		
Weight			15kg		
*1: This is the	value at a co	nstant ambient tempe	rature. (X. Y axes)		



YK400XP

- *1: This is the value at a constant ambient temperature. (X, Y a *2: There are limits to the setting of the acceleration coefficient.





